

SIGNALS AND SYSTEMS

Subject Code: **(EC304PC)**

Regulations : R18JNTUH

Class : II Year B.Tech ECE I Semester



Department of Electronics and communication Engineering

BHARAT INSTITUTE OF ENGINEERING AND TECHNOLOGY

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SIGNALS AND SYSTEMS (EC304PC) COURSE PLANNER

I. COURSE OVERVIEW:

Signals and Systems encounter extensively in our day-to-day lives, from making a phone call, listening to a song, editing photos, manipulating audio files, using speech recognition software's like Siri and Google now, to taking EEGs, ECGs and X-Ray images. Each of these involves gathering, storing, transmitting and processing information from the physical world.

This course will equip to deal with these tasks efficiently by learning the basic mathematical framework of signals and systems. Here we will explore the various properties of signals and systems, characterization of Linear Time Invariant Systems/ Time variant systems, convolution and Fourier Series and Transform, and also deal with the Sampling theorem, Z-Transform, Correlation and Laplace transform. Ideas introduced in this course will be useful in understanding further Electronic/ Electrical Engineering courses which deal with control systems, communication systems, digital signal processing, statistical signal analysis and digital message transmission. Further concepts such as signal sampling and aliasing are introduced. The theory is exemplified with processing of signals in MATLAB.

II. PREREQUISITS:

1. Engineering Mathematics
2. Basics of Vector Theory

III. COURSE OBJECTIVES:

1.	This gives the basics of Signals and Systems required for all Electrical Engineering related courses.
2.	To understand the behavior of signal in time and frequency domain
3.	To understand the characteristics of LTI systems
4.	This gives concepts of Signals and Systems and its analysis using different transform techniques.

IV. COURSE OUTCOMES:

S.No.	Description	Bloom's Taxonomy Level
1.	Differentiate various signal functions.	Remember, Understand (Level1, Level2)
2.	Represent any arbitrary signal in time and frequency domain.	Apply, (Level 3)
3.	Understand the characteristics of linear time invariant systems.	Remember, Understand (Level1, Level2)
4.	Analyze the signals with different transform technique.	Analyze (Level 4)

V. HOW PROGRAM OUTCOMES ARE ASSESSED:

Program Outcomes (PO)		Level	Proficiency assessed by
PO1	Engineering Knowledge: Apply the knowledge of mathematics, science, engineering fundamentals, and an engineering specialization to the solution of complex engineering problems.	3	Assignments, Exercises
PO2	Problem Analysis: Identify, formulate, review research literature, and analyze complex engineering problems reaching substantiated conclusions using first principles of mathematics, natural sciences, and engineering sciences.	3	Assignments
PO3	Design/ Development of Solutions: Design solutions for complex engineering problems and design system components or processes that meet the specified needs with appropriate consideration for the public health and safety, and the cultural, societal, and environmental considerations.	1	Assignments
PO4	Conduct Investigations of Complex Problems: Use research-based knowledge and research methods including design of experiments, analysis and interpretation of data, and synthesis of the information to provide valid conclusions.	-	-
PO5	Modern Tool Usage: Create, select, and apply appropriate techniques, resources, and modern engineering and IT tools including prediction and modeling to complex engineering activities with an understanding of the limitations.	1	Assignments
PO6	The Engineer and Society: Apply reasoning informed by the contextual knowledge to assess societal, health, safety, legal and cultural issues and the consequent responsibilities relevant to the professional engineering practice.	-	-
PO7	Environment and Sustainability: Understand the impact of the professional engineering solutions in societal and environmental contexts, and demonstrate the knowledge of, and need for sustainable development.	-	-
PO8	Ethics: Apply ethical principles and commit to professional ethics and responsibilities and norms of the engineering practice.	-	-
PO9	Individual and Team Work: Function effectively as an individual, and as a member or leader in diverse teams, and in multidisciplinary settings.	2	Oral Discussions
PO10	Communication: Communicate effectively on complex engineering activities with the engineering community and with society at large, such as, being able to comprehend and write effective reports and design documentation, make effective presentations, and give and receive clear instructions.	-	-
PO11	Project management and finance: Demonstrate knowledge and understanding of the engineering and management principles and apply these to one's own work, as a member and leader in a team, to manage projects and in multidisciplinary environments.	-	-
PO12	Life-Long Learning: Recognize the need for, and have the preparation and ability to engage in independent and life-long learning in the broadest context of technological change.	1	Assignments

1: Slight (Low) 2: Moderate (Medium) 3: Substantial (High) - : None

VI. HOW PROGRAM SPECIFIC OUTCOMES ARE ASSESSED:

Program Specific Outcomes		Level	Proficiency assessed by
PSO 1	Professional Skills: An ability to understand the basic concepts in Electronics & Communication Engineering and to apply them to various areas, like Electronics, Communications, Signal processing, VLSI, Embedded systems etc., in the design and implementation of complex systems.	1	Lectures, Assignments
PSO 2	Problem-Solving Skills: An ability to solve complex Electronics and communication Engineering problems, using latest hardware and software tools, along with analytical skills to arrive cost effective and appropriate solutions.	3	Tutorials
PSO 3	Successful Career and Entrepreneurship: An understanding of social-awareness & environmental-wisdom along with ethical responsibility to have a successful career and to sustain passion and zeal for real-world applications using optimal resources as an Entrepreneur.	-	-

1: Slight (Low) 2: Moderate (Medium) 3: Substantial (High) - : None

VII. SYLLABUS:

UNIT - I Signal Analysis: Analogy between Vectors and Signals, Orthogonal Signal Space, Signal approximation using Orthogonal functions, Mean Square Error, Closed or complete set of Orthogonal functions, Orthogonality in Complex functions, Classification of Signals and systems, Exponential and Sinusoidal signals, Concepts of Impulse function, Unit Step function, Signum function.

UNIT – II Fourier series: Representation of Fourier series, Continuous time periodic signals, Properties of Fourier Series, Dirichlet’s conditions, Trigonometric Fourier Series and Exponential Fourier Series, Complex Fourier spectrum.

Fourier Transforms: Deriving Fourier Transform from Fourier series, Fourier Transform of arbitrary signal, Fourier Transform of standard signals, Fourier Transform of Periodic Signals, Properties of Fourier Transform, Fourier Transforms involving Impulse function and Signum function, Introduction to Hilbert Transform.

UNIT - III Signal Transmission through Linear Systems: Linear System, Impulse response, Response of a Linear System, Linear Time Invariant(LTI) System, Linear Time Variant (LTV) System, Transfer function of a LTI System, Filter characteristic of Linear System, Distortion less transmission through a system, Signal bandwidth, System Bandwidth, Ideal LPF, HPF, and BPF characteristics, Causality and Paley-Wiener criterion for physical realization, Relationship between Bandwidth and rise time, Convolution and Correlation of Signals, Concept of convolution in Time domain and Frequency domain, Graphical representation of Convolution.

UNIT – IV Laplace Transforms: Laplace Transforms (L.T), Inverse Laplace Transform, Concept of Region of Convergence (ROC) for Laplace Transforms, Properties of L.T, Relation between L.T and F.T of a signal, Laplace Transform of certain signals using waveform synthesis.

Z-Transforms: Concept of Z- Transform of a Discrete Sequence, Distinction between Laplace, Fourier and Z Transforms, Region of Convergence in Z-Transform, Constraints on ROC for various classes of signals, Inverse Z-transform, Properties of Z-transforms.



UNIT - V Sampling Theorem: Graphical and analytical proof for Band Limited Signals, Impulse Sampling, Natural and Flat top Sampling, Reconstruction of signal from its samples, Effect of under sampling – Aliasing, Introduction to Band Pass Sampling.

Correlation: Cross Correlation and Auto Correlation of Functions, Properties of Correlation Functions, Energy Density Spectrum, Parsevals Theorem, Power Density Spectrum, Relation between Autocorrelation Function and Energy/Power Spectral Density Function, Relation between Convolution and Correlation, Detection of Periodic Signals in the presence of Noise by Correlation, Extraction of Signal from Noise by Filtering.

TEXT BOOKS:

1. Signals, Systems & Communications - B.P. Lathi, 2013, BSP.
2. Signals and Systems - A.V. Oppenheim, A.S. Willsky and S.H. Nawabi, 2 Ed.

REFERENCE BOOKS:

1. Signals and Systems – Simon Haykin and Van Veen, Wiley 2 Ed.,
2. Signals and Systems – A. Rama Krishna Rao, 2008, TMH
3. Fundamentals of Signals and Systems - Michel J. Robert, 2008, MGH International Edition.
4. Signals, Systems and Transforms -C.L.Philips, J.M.Parr and Eve A.Riskin,3Ed.,2004, PE.
5. Signals and Systems – K. Deergha Rao, Birkhauser, 2018.

NPTEL Web Course: <https://nptel.ac.in/courses/108104100>

NPTEL Video Course: <https://nptel.ac.in/courses/108104100>

GATE SYLLABUS:

Definitions and properties of Laplace transform, continuous-time and discrete-time Fourier series, continuous-time and discrete-time Fourier Transform, DFT and FFT, z-transform. Sampling theorem. Linear Time-Invariant (LTI) Systems: definitions and properties; causality, stability, impulse response, convolution, poles and zeros, parallel and cascade structure, frequency response, group delay, phase delay. Signal transmission through LTI systems.

IES SYLLABUS:

Classification of signals and systems: System modeling in terms of differential and difference equations; State variable representation; Fourier series; Fourier transforms and their application to system analysis; Laplace transforms and their application to system analysis; Convolution and superposition integrals and their applications; Z-transforms and their applications to the analysis and characterization of discrete time systems; Random signals and probability, Correlation functions; Spectral density; Response of linear system to random inputs.

VIII. COURSE PLAN (WEEK-WISE):

Lecture No.	Unit No	Course Learning Outcome	Topics Covered	Teaching Methodology	Text Book/ Reference
1-4	1	Discuss the analogy between vectors and signals. Describe the signal approximation using orthogonal functions	Analogy between vectors and signals, Orthogonal signal space, Signal approximation using orthogonal functions, Mean square error, Closed or complete set of orthogonal functions	Chalk and Talk	T1, T2, R1
5-8		Discuss about Exponential and sinusoidal signals, Concepts of Impulse function, Unit step function, Signum function.	Orthogonality in complex functions Exponential and sinusoidal signals, Concepts of Impulse function, Unit step function, Signum function.	Chalk and Talk	T1, T2, R1
9-12	2	Illustrate Fourier series, Continuous time periodic signals, properties of Fourier series	Representation of Fourier series, Continuous time periodic signals, properties of Fourier series,	Chalk and Talk	T1, T2, R1
13-17		Illustrate Dirichlet's conditions, Trigonometric Fourier series and Exponential Fourier series, Complex Fourier spectrum	Dirichlet's conditions, Trigonometric Fourier series and Exponential Fourier series, Complex Fourier spectrum	Chalk and Talk	T1, T2, R1
18-20		Compute Fourier transform from Fourier series, Fourier transform of arbitrary signal, Fourier transform of standard signals, Fourier transform of periodic signals	Deriving Fourier transform from Fourier series, Fourier transform of arbitrary signal, Fourier transform of standard signals, Fourier transform of periodic signals	Chalk and Talk	T1, T2, R1
21-24		Illustrate the Properties of Fourier transforms, Fourier transforms involving impulse function and Signum function and Introduction to Hilbert Transform.	Properties of Fourier transforms, Fourier transforms involving impulse function and Signum function, Introduction to Hilbert Transform.	Chalk and Talk	T1, T2, R1
25-26		Demonstration of Linear system, impulse response, Response of a linear system, Linear time invariant (LTI) system, Linear time variant (LTV) system. compute Transfer function of a LTI	Linear system, impulse response, Response of a linear system, Linear time invariant (LTI) system, Linear time variant (LTV) system, Transfer function of a LTI system.	Chalk and Talk	T1, T2, R1

	3	system.			
27-28		Discuss Filter characteristics of linear systems, . Distortion less transmission through a system, Signal bandwidth, system bandwidth, Ideal LPF, HPF and BPF characteristics,	Filter characteristics of linear systems. Distortion less transmission through a system, Signal bandwidth, system bandwidth, Ideal LPF, HPF and BPF characteristics,	Chalk and Talk	T1, T2, R1
29-30		Demonstrate the Causality and Paley-Wiener criterion for physical realization,, Analyze Relationship between bandwidth and rise time	Causality and Paley-Wiener criterion for physical realization, Relationship between bandwidth and rise time.	Chalk and Talk	T1, T2, R1
31-34		Describe Laplace transforms, Partial fraction expansion, Inverse Laplace transform,	Review of Laplace transforms, Partial fraction expansion, Inverse Laplace transform, Concept of region of	Chalk and Talk	T1, T2, R1
		Concept of region of Laplace transforms.	convergence (ROC) for Laplace transforms.	Chalk and Talk, PPT	T1, T2, R1
35-38	4	Examine the constraints on ROC for various classes of signals Describe Properties of L.T's relation between L.T's, and F.T. of a signal. Laplace transform of certain signals using waveform synthesis.	Constraints on ROC for various classes of signals, Properties of L.T's relation between L.T's, and F.T. of a signal. Laplace transform of certain signals using waveform synthesis.	Chalk and Talk	T1, T2, R1
39-40		Examine the fundamental difference between continuous and discrete time signals Analyze discrete time signal representation using complex exponential and sinusoidal components, Periodicity of discrete time using complex exponential signal	Fundamental difference between continuous and discrete time signals, discrete time signal representation using complex exponential and sinusoidal components, Periodicity of discrete time using complex exponential signal	Chalk and Talk	T1, T2, R1

41-44		Describe concept of Z-Transform of a discrete sequence, Distinction between Laplace, Fourier and Z transforms, Region of convergence in Z-Transform, constraints on ROC for various classes of signals	Concept of Z- Transform of a discrete sequence, Distinction between Laplace, Fourier and Z transforms, Region of convergence in Z-Transform, constraints on ROC for various classes of signals	Chalk and Talk	T1, T2, R1
45-48	5	Illustrate Sampling theorem and , Types of sampling	Sampling theorem – Graphical and analytical proof for Band Limited Signals, Types of sampling-impulse sampling, Natural and Flat top Sampling	Chalk and Talk	T1, T2, R1
49-51		Illustrate Reconstruction of signal from its samples, effect of undersampling	Reconstruction of signal from its samples, effect of under sampling – Aliasing, Introduction to Band Pass sampling.	Chalk and Talk	T1, T2, R1
52-56		Demonstrate cross correlation and auto correlation of functions, properties of correlation function, Energy density spectrum, Parseval's theorem, Power density spectrum	Cross correlation and auto correlation of functions, properties of correlation function, Energy density spectrum, Parseval's theorem, Power density spectrum	Chalk and Talk	T1, T2, R1
57-59		Discuss relation between autocorrelation function and energy/power spectral density function Express Relation between convolution and correlation	Relation between autocorrelation function and energy/power spectral density function, Relation between convolution and correlation	Chalk and Talk	T1, T2, R1
60-62		Discuss the detection of signal from noise by filtering.	Detection of periodic signals in the presence of noise by correlation, Extraction of signal from noise by filtering.	Chalk and Talk, PPT	T1, T2, R18

IX. MAPPING COURSE OUTCOMES LEADING TO THE ACHIEVEMENT OF PROGRAM OUTCOMES AND PROGRAM SPECIFIC OUTCOMES:

Course Outcomes	Program Outcomes												Program Specific Outcomes		
	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2	PSO3
CO1	3	3	1	-	1	-	-	-	1	-	-	1	1	3	-
CO2	3	3	1	-	1	-	-	-	1	-	-	1	1	3	-
CO3	3	3	1	-	1	-	-	-	2	-	-	1	1	3	-
CO4	3	3	2	-	1	-	-	-	2	-	-	1	1	3	-
Average	3	3	1.25	-	1	-	-	-	1.5	-	-	1	1	3	-
Average (Rounded)	3	3	1	-	1	-	-	-	2	-	-	1	1	3	-

1: Slight (Low) 2: Moderate (Medium) 3: Substantial (High) - : None

X. JUSTIFICATIONS FOR CO-PO MAPPING:

Mapping	Low (1), Medium (2), High(3)	Justification
CO1-PO1	3	Students will be able to discuss the analogy between vectors and signals.
CO1-PO2	3	Students will be able to describe the signal approximation using orthogonal functions.
CO1-PO3	1	Students will be able to discuss about Exponential and sinusoidal signals, Concepts of Impulse function, Unit step function, Signum function.
CO1-PO5	1	Students will be able to illustrate Fourier series, Continuous time periodic signals, properties of Fourier series.
CO1-PO9	1	Students will be able to illustrate Dirichlet's conditions, Trigonometric Fourier series and Exponential Fourier series, Complex Fourier spectrum.
CO1-PO12	1	Students will be able to compute Fourier transform from Fourier series.
CO1-PSO1	1	Students will be able to compute Fourier transform of arbitrary signal.
CO1-PSO2	3	Students will be able to compute Fourier transform of standard signals.
CO2-PO1	3	Students will be able to compute Fourier transform of periodic signals.
CO2-PO2	3	Students will be able to demonstrate the Linear system, impulse response, Response of a linear system, Linear time invariant (LTI) system, and Linear time variant (LTV) system.
CO2-PO3	1	Students will be able to discuss Filter characteristics of linear systems.
CO2-PO5	1	Students will be able to demonstrate the Causality and Paley-Wiener criterion for physical realization.
CO2-PO9	1	Students will be able to describe Laplace transforms, Partial fraction expansion, Inverse Laplace transform.
CO2-PO12	1	Students will be able to demonstrate the concept of region of

		convergence (ROC) for Laplace transforms.
CO2-PSO1	1	Students will be able to examine the constraints on ROC for various classes of signals.
CO2-PSO2	3	Students will be able to examine the fundamental difference between continuous and discrete time signals.
CO3-PO1	3	Students will be able to describe concept of Z- Transform of a discrete sequence.
CO3-PO2	3	Students will be able to describe concept and methods to determine the inverse Z- Transform of a discrete sequence.
CO3-PO3	1	Students will be able to describe concept of Z- Transform of a discrete sequence.
CO3-PO5	1	Students will be able to explain the distinction between Laplace, Fourier and Z transforms, Region of convergence in Z-Transform,.
CO3-PO9	2	Students will be able to explain the constraints on ROC for various classes of signals
CO3-PO12	1	Students will be able to illustrate Sampling theorem.
CO3-PSO1	1	Students will be able to illustrate the types of sampling.
CO3-PSO2	3	Students will be able to illustrate Reconstruction of signal from its samples.
CO4-PO1	3	Students will be able to illustrate the effects of undersampling.
CO4-PO2	3	Students will be able to demonstrate cross correlation.
CO4-PO3	2	Students will be able to demonstrate properties of correlation function.
CO4-PO5	1	Students will be able to demonstrate Energy density spectrum, Parseval's theorem.
CO4-PO9	2	Students will be able to demonstrate Power density spectrum.
CO4-PO12	1	Students will be able to discuss relation between autocorrelation function and energy spectral density
CO4-PSO1	1	Students will be able to discuss relation between autocorrelation function and power spectral density
CO4-PSO2	3	Students will be able to express Relation between convolution and correlation.

XI. QUESTION BANK (JNTUH):

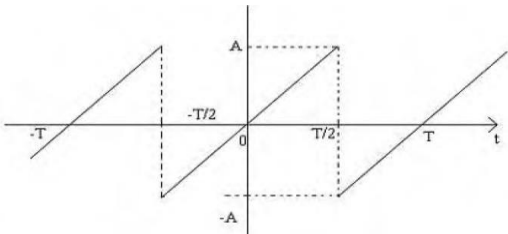
UNIT - I

Long Answer Questions:

S.No.	Question	Blooms Taxonomy Level	Course Outcome
1.	Write the classification of all the standard signals	Remember	1
2.	Prove that $\sin n\omega t$ and $\cos m\omega t$ are orthogonal to each other for all integers m, n	Apply	1
3.	Prove that the complex exponential signals are orthogonal functions $x(t)=e^{jn\omega t}$ and $y(t)=e^{jm\omega t}$ let the interval be (t_0, t_0+T)	Apply	1
4.	Discuss how an unknown function $f(t)$ can be expressed using infinite Mutually orthogonal functions. Hence show the representation of a	Apply	1

	waveform $f(t)$ using trigonometric Fourier series.		
5.	Explain the analogy of vectors and signals in terms of orthogonality and evaluation of constant.	Understand	1

Short Answer Questions:

S.No.	Question	Blooms Taxonomy Level	Course Outcome
1.	Define the following basic signals with graphical representation i) Unit Sample Signal ii) Unit Step Signal iii) Ramp Signal iv) Sinusoidal signal.	Remember	1
2.	Write short notes on “orthogonal vector space”	Understand	1
3.	List out all the properties of Fourier Series.	Understand	1
4.	Determine the Fourier series of the function shown in figure 	Remember	1
5.	Give relationship between Trigonometric and Exponential Fourier series.	Understand	1

UNIT - II

Long Answer Questions:

S.No.	Question	Blooms Taxonomy Level	Course Outcome
1.	Find the Fourier transform of the function i) $f(t) = e^{-a t } \sin at$ ii) $f(t) = \cos at$ iii) $f(t) = \sin at$	Apply	2
2.	Find the even and odd components of the signal $x(t) = \cos(\omega t + \pi/3)$.	Understand	2
3.	A rectangular function $f(t)$ is defined by $f(t) = 1; 0 < t < \pi$ $= -1; \pi < t < 2\pi$ Approximate this function by a waveform $\sin t$ over the interval $(0, 2\pi)$ such that the mean square error is inimum.	Understand	2
4.	Show that autocorrelation and power spectral density form a Fourier Transform Pair.	Understand	2
5.	State and prove Parseval's Theorem.	Remember	2



Short Answer Questions:

S.No.	Question	Blooms Taxonomy Level	Course Outcome
1.	State and prove any Four Properties of Fourier Transform.	Remember	2
2.	Briefly explain Dirichlet's conditions for Fourier series	Understand	2
3.	State Time Shifting property in relation to Fourier series.	Understand	2
4.	Find the fourier transform of $x(t)=\sin(\omega t)$	Understand	2
5.	Write the standard forms three classes of Fourier series	Evaluate	2

UNIT - III

Long Answer Questions:

S.No.	Question	Blooms Taxonomy Level	Course Outcome
1.	A system represented by $y(t) = 2x(t-2) + 2x(t+2)$. i) Is the system time invariant? Justify your answer. ii) Is the system causal? Justify your answer.	Remember	3
2.	Define Linearity and Time-Invariant properties of a system.	Understand	3
3.	Show that the output of an LTI system is given by the linear convolution of input signal and impulse response of the system.	Understand	3
4.	What are the requirements to be satisfied by an LTI system to provide distortion less transmission of a signal?	Understand	3
5.	Bring out the relation between bandwidth and rise time	Understand	3

Short Answer Questions:

S.No.	Question	Blooms Taxonomy Level	Course Outcome
1.	Define the terms: i) Signal Bandwidth ii) System bandwidth	Remember	3
2.	Define the terms: Linear time Variant system Paley-wiener criteria for physical reliability.	Remember	3
3.	Discuss the effect of aliasing due to under sampling.	Understand	3
4.	Briefly explain BIBO stability concept.	Remember	3
5.	State Convolution property of Fourier Transform.	Analyze	3

UNIT - IV

Long Answer Questions:



S.No.	Question	Blooms Taxonomy Level	Course Outcome
1.	Find the inverse Z transform of $X(z) = \ln(1+az^{-1})$; ROC $ z >a$	Understand	4
2.	State and Prove Initial value and Final value theorem w.r.t Laplace transform	Remember	4
3.	State any four properties of Laplace transform.	Understand	4
4.	Find the inverse Laplace transform of $(S-1) / (S) (S+1)$.	Understand	4
5.	Bring out the relationship between Laplace and Fourier Transform.	Analyze	4

Short Answer Questions:

S.No.	Question	Blooms Taxonomy Level	Course Outcome
1.	Define Laplace Transform and Its inverse.	Remember	4
2.	Define Region of convergence and state its properties.	Remember	4
3.	Find the Laplace transform of $f(t) = \sin at \cos bt$ & $f(t) = t \sin at$	Understand	4
4.	State the properties of the ROC of Laplace transform	Remember	4
5.	Define Region of Convergence and state its properties w.r.t Z-Transform.	Remember	4

UNIT - V

Long Answer Questions:

S.No.	Question	Blooms Taxonomy Level	Course Outcome
1.	State and prove sampling theorem for band limited signals	Understand	4
2.	Derive the relationship between autocorrelation function and energy spectral density of an energy signal.	Understand	4
3.	Discuss the process of reconstructing the signal from its samples.	Understand	4
4.	Bring out the relation between Correlation and Convolution.	Remember	4
5.	Define Nyquist rate. Compare the merits and demerits of performing sampling using impulse, Natural and Flat-top sampling techniques.	Remember	4

Short Answer Questions:

S.No.	Question	Blooms	Course
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		Taxonomy Level	Outcome
1.	Find the convolution of two signals $x(n) = \{ 1, 1, 0, 1, 1 \}$ and $h(n) = \{ 1, -2, -3, 4 \}$	Remember	4
2.	Define autocorrelation and state its properties.	Remember	4
3.	What is the condition for avoid the aliasing effect?	Understand	4
4.	What is the significance of antialiasing filter	Analyze	4
5.	Define sampling of band pass signals.	Analyze	4

OBJECTIVE QUESTIONS:

UNIT I

1. The type of systems which are characterized by input and the output quantized at certain levels are called as _____. []
a) analog b) discrete c) continuous d) digital
2. The type of systems which are characterized by input and the output capable of taking any value in a particular set of values are called as _____. []
a) analog b) discrete c) digital d) continuous
3. An example of a discrete set of information/system is _____. []
a) the trajectory of the Sun b) data on a CD
c) universe time scale d) movement of water through a pipe
4. A system which is linear is said to obey the rules of _____. []
a) scaling b) additivity c) both scaling and additivity d) homogeneity
5. A time invariant system is a system whose output _____. []
a) increases with a delay in input b) decreases with a delay in input
c) remains same with a delay in input d) vanishes with a delay in input
6. Basically signals can be broadly classified as &
7. The condition for Orthogonality between two time domain signals is.....
8. The condition for periodicity of a continuous time signal is.....
9. The equation for finding the power of DT signal is.....
10. The Fourier Series of a continuous time signal is defined as.....

UNIT II

1. _____ discovered Fourier series. []
a) Jean Baptiste de Fourier b) Jean Baptiste Joseph Fourier
c) Fourier Joseph d) Jean Fourier
2. _____ are the conditions which are required for a signal to fulfil to be represented as Fourier series. []
a) Dirichlet's conditions b) Gibbs phenomenon
c) Fourier conditions d) Fourier phenomenon
3. _____ are the two types of Fourier series. []
a) Trigonometric and exponential b) Trigonometric and logarithmic

- c) Exponential and logarithmic d) Trigonometric only
4. _____ are the Fourier coefficients in the following. []
 a) a_0, a_n and b_n b) a_n c) b_n d) a_n and b_n
5. _____ is the disadvantage of exponential Fourier series. []
 a) It is tough to calculate b) It is not easily visualized
 c) It cannot be easily visualized as sinusoids d) It is hard for manipulation
6. The Fourier transform of $x(t)$ is given by.....
7. Fourier transform is used to analyze asignal in frequency domain.
8. The inverse Fourier transform of $X(\omega)$ is given by.....
9. is the Fourier transform of a delta function.
10. According to sampling theorem the frequency of sampling f_s should be

UNIT III

1. The rule $h*x = x*h$ is called _____. []
 a) Commutativity rule b) Associativity rule c) Distributive rule d) Transitive rule
2. For an LTI discrete system to be stable, the square sum of the impulse response should be _____. []
 a) Integral multiple of 2π b) Infinity c) Finite d) Zero
3. The rule $(h*x)*c = h*(x*c)$ is called _____. []
 a) Commutativity rule b) Associativity rule c) Distributive rule d) Transitive rule
4. The system $h(t) = \exp(-7t)$ correspond to a _____ system. []
 a) Yes b) No c) Marginally Stable d) None
5. _____ expression equal to: $h*(d+bd)$, $d(t)$ is the delta function. []
 a) $h + d$ b) $b + d$ c) d d) $h + b$
6. A continuous time system is timeif the time shift is reflected in the output signal also.
7. The equation for transfer function of a system is given by the ratio of&
8. _____ defines impulse response of a continuous time system.
9. The range of frequencies of an ideal low pass filter will be from.....Hz to.....Hz
10. If a system is causal then the condition in terms of the impulse response $h(t)$ is....

UNIT IV

1. Transfer function may be defined as _____. []
 a) Ratio of out to input b) Ratio of Laplace transform of output to input
 c) Ratio of Laplace transform of output to input with zero initial conditions d) None
2. _____ are the poles of transfer function which is defined by input $x(t)=5\sin(t)-u(t)$ and output $y(t)=\cos(t)-u(t)$. []
 a) 4.79, 0.208 b) 5.73, 0.31 c) 5.89, 0.208 d) 5.49, 0.308
3. Any system is said to be stable if and only if _____. []
 a) Its poles lie at the left of imaginary axis b) Its zeros lie at the left of imaginary axis
 c) Its poles lie at the right of imaginary axis d) Its zeros lie at the right of imaginary axis
4. _____ justifies the linearity property of z-transform $[x(n) \leftrightarrow X(z)]$. []
 a) $x(n)+y(n) \leftrightarrow X(z)Y(z)$ b) $x(n)+y(n) \leftrightarrow X(z)+Y(z)$

- c) $x(n)y(n) \leftrightarrow X(z)+Y(z)$ d) $x(n)y(n) \leftrightarrow X(z)Y(z)$
5. _____ is the set of all values of z for which $X(z)$ attains a finite value. []
- a) Radius of convergence b) Radius of divergence
- c) Feasible solution d) None of the mentioned
6. The mathematical computation called..... is used to represent continuous time signals in terms of complex exponentials.
7. The Laplace transform of $x(t)=e^{-at}u(t)$ is.....
8. The time delay property of Laplace transform is given by
9. _____ are two advantages of Laplace transforms.
10. The inverse Laplace transform of $X(s)$ is given by

UNIT V

1. The value of $h[n]*d[n-1]$, $d[n]$ being the delta function is _____. []
- a) $h[n-2]$ b) $h[n]$ c) $h[n-1]$ d) $h[n+1]$
2. The convolution of $x(t) = \exp(2t)u(-t)$, and $h(t) = u(t-3)$ is _____. []
- a) $0.5\exp(2t-6) u(-t+3) + 0.5u(t-3)$ b) $0.5\exp(2t-3) u(-t+3) + 0.8u(t-3)$
- c) $0.5\exp(2t-6) u(-t+3) + 0.5u(t-6)$ d) $0.5\exp(2t-6) u(-t+3) + 0.8u(t-3)$
3. The convolution of $x(t) = \exp(3t)u(-t)$, and $h(t) = u(t-3)$ is _____. []
- a) $0.33\exp(2t-6) u(-t+3) + 0.5u(t-3)$ b) $0.5\exp(4t-3) u(-t+3) + 0.8u(t-3)$
- c) $0.33\exp(2t-6) u(-t+3) + 0.5u(t-6)$ d) $0.33\exp(3t-6) u(-t+3) + 0.33u(t-3)$
4. The value of $d(t-34)*x(t+56)$, $d(t)$ being the delta function is _____. []
- a) $x(t + 56)$ b) $x(t + 32)$ c) $x(t + 22)$ d) $x(t - 22)$
5. If h_1, h_2 and h_3 are cascaded, the overall impulse response is _____. []
- a) $h_1 * h_2 * h_3$ b) $h_1 + h_2 + h_3$ c) h_3 d) all of the above
6. The equation for convolution in time domain is
7. Convolution sum is the mathematical computation that can be performed only on signals.
8. $x(n).\delta(n-n_0) = \dots\dots\dots$
9. The spectral density functions of the periodic or non-periodic signal $x(t)$ represents the distribution of power or energy in the domain.
10. If $X(f)$ is the frequency domain function of a signal $x(t)$ then its ESD is given as

XII. WEBSITES:

- <https://www.edx.org/course/signals-systems-part-1-iitbombay-ee210-1x-1>
- nptel.ac.in/courses/117104074
- dsp.rice.edu/courses/elec301

XIII. EXPERT DETAILS:

- Mr. S. Srinivasan, Professor, Indian Institute of Technology, Madras
- Dr. V. Sumalatha (JNTUA)
- Dr. P. V. D. Somasekhar Rao (JNTUH)

4. Dr. T.Satya Savithri (JNTUH)

**XIV. JOURNALS:
INTERNATIONAL**

1. IEEE Journal on Selected Areas in Communications
2. IEEE Transactions on Signal Processing
3. IEEE Transactions on Circuits and Systems
4. IEEE Transactions on Audio, Speech, and Language Processing

NATIONAL

1. The Journal of the Acoustical Society of America
2. EURASIP Journal on Advances in Signal Processing
3. Journal of Signal Processing Systems

XV. LIST OF TOPICS FOR STUDENT SEMINARS:

1. Signal approximation using orthogonal functions.
2. Fourier series representation of periodic signals.
3. Fourier series properties.
4. Fourier transforms properties.
5. Signal transmission through linear systems.

XVII. CASE STUDIES / SMALL PROJECTS:

1. Estimation of Improved DFT Characteristics.
2. Calculation Fourier Transform using Mat Lab.
3. Designing of an LTI System.